Finding Points on Elliptic Curves in Deterministic Polynomial Time (odd characteristic)

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The Question

We are given a finite field $\mathbb F$ with $q=p^e$ elements, and an equation

$$Y^{2} + a_{1}XY + a_{3}Y = X^{3} + a_{2}X^{2} + a_{4}X + a_{6}$$

with coefficients $a_i \in \mathbb{F}$ (a cubic Weierstrass equation).

Question: compute $x, y \in \mathbb{F}$ that satisfy the equation.

Well-known: if the curve defined by the equation is nonsingular, its projective closure is an elliptic curve over \mathbb{F} , i.e., a curve of genus 1 with a specified \mathbb{F} -rational point — which is at infinity.

Answers

First try:

- 1. Guess a value for X.
- 2. See if the resulting quadratic equation in Y is solvable. If not, go to step 1.
- 3. Solve it using a probabilistic root taking algorithm (Tonelli-Shanks, or Cantor-Zassenhaus).

Question (Schoof 1985): is there an efficient deterministic algorithm?

Answer: yes, there is! The algorithm I will present

- is long and complicated...
- uses group theory, theory of algebras and some geometry
- takes about cubic time in $\log q$ when using fast arithmetic

Reductions

We assume char $\mathbb{F} \neq 2$ — for the case of characteristic 2, listen to the next talk.

Now we can complete the square, and get a simpler Weierstrass equation

$$Y^{2} = X^{3} + aX^{2} + bX + c =_{def} f(X).$$

This equation is singular iff f(X) has a double root in \mathbb{F} .

In the singular case, it is easy to compute the coordinates of the singular point; and in fact, we can use this point to parametrise the entire curve.

For the rest of the talk, the equation $Y^2 = f(X)$ is supposed to be nonsingular.

Geometric setting

Let E be an elliptic curve over \mathbb{F} , and consider the threefold

 $E \times E \times E$.

The curve E possesses an elliptic involution

$$-1: E
ightarrow E: (x,y) \mapsto (x,-y), \mathcal{O} \mapsto \mathcal{O}.$$

Thus, on E^3 , there is an action of $G = \{\pm 1\}^3$. Consider the subgroup H of G consisting of

$$\{(1,1,1),(-1,-1,1),(-1,1,-1),(1,-1,-1)\},\$$

a Klein 4-group.

Geometric setting (II)

We construct the quotient of E^3 with respect to the action of H, and get a (very singular) threefold

$$V = E^3/H.$$

Doing some Galois theory on the function field of E^3 , we find an affine model of V:

$$V : f(X_1)f(X_2)f(X_3) = Y^2.$$

(The idea of using this threefold is due to Mariusz Skałba.) (In characteristic 2, there is a comparable model — see next talk.)

We will solve two subproblems:

- 1. Show how to construct points on V;
- 2. Show how every point P on V leads to a point on E.

On square roots

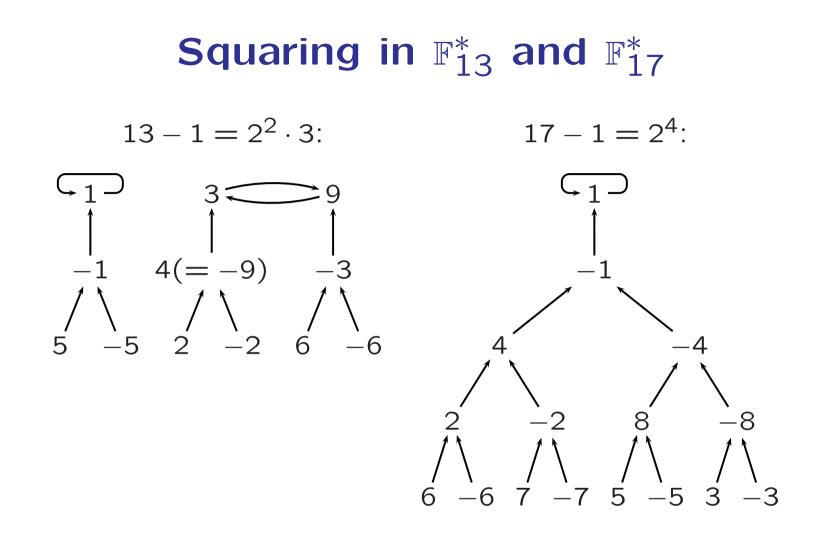
We first treat the latter question. Observe that if

 $f(x_1)f(x_2)f(x_3)$

is a square y^2 , then at least one of the $f(x_i)$ is a square itself.

Lemma. If $a, b \in \mathbb{F}^*$ are such that ord(b) has more factors 2 than ord(a), then a deterministic variant of the Tonelli-Shanks algorithm can compute a square root of a using b.

But even if all three of $\operatorname{ord}(f(x_i))$ have equally many factors 2, then $\operatorname{ord} y$ must have more! So in any case, we can get a square root of at least one of the $f(x_i)$.



The level of an element in the tree (where the root has level 0) is equal to the number of factors 2 in its order!

A rationally ruled surface

The first step to finding points on the threefold \boldsymbol{V} is a rational map

 $\phi: S \to V$

where S is a rationally ruled surface over \mathbb{F} .

Most of the ruling curves on S are conic sections over $\mathbb F,$ and we have

Theorem. There exists a deterministic efficient algorithm that can solve an equation

$$ax^2 + by^2 = c$$

over a finite field.

Having a rational point, we can easily parametrise the conic section, and thus parametrise a genus 0 curve on the threefold V.

Solving quadratic equations

Given an equation $ax^2 + by^2 = c$, with $abc \neq 0$, we first divide by c to get

$$ax^2 + by^2 = 1.$$

If ord(a) has more factors 2 than ord(b), we can take a square root of b.

If the levels of a and b are equal, then this common level is:

0: we can take square roots of a and b anyway

> 1: we can take a square root of -a/b and get $ax^2 - ay^2 = 1$

1: we can take square roots of -a and -b and get $x^2 + y^2 = -1$.

The last one is tricky; I use a "bisection" to solve it.

Geometric details

The surface S is given by

$$y^2h(u,v) = -f(u)$$

where

$$h(u, v) = u^{2} + uv + v^{2} + a(u + v) + b$$

is such that h(u, u) = f'(u).

Computations in the étale algebra $\mathbb{F}[X]/(f)$ show that the rational map

$$(u, v, y) \mapsto \left(u, -a - u - v, u + y^2, -\frac{f(u)f(u + y^2)}{y^3}\right)$$

sends points on S to V (see the proceedings article).

Norms in the elliptic algebra

Consider $R = \mathbb{F}[X]/(f) = \mathbb{F}[\theta]$. Using the norm from R to \mathbb{F} , we see that, for any $a \in \mathbb{F}$,

$$\operatorname{Norm}(a-\theta) = f(a).$$

Thus, we consider

$$\phi(u, v, w) = (u - \theta)(v - \theta)(w - \theta)$$

and hope that its norm will be a square. If we stipulate a + u + v + w = 0, then

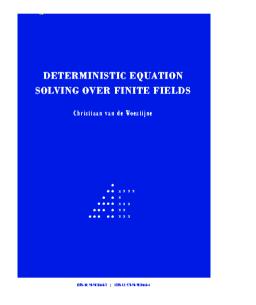
$$f(u)f(v)f(w) = \operatorname{Norm} \phi(u, v, w) = -h(u, v)^{3} f\left(u - \frac{f(u)}{h(u, v)}\right).$$

So, if we restrict ourselves to the surface S defined by

$$-f(u) = y^2 h(u, v) \dots$$

Proofs...

of the results on square roots and quadratic equations are in my Ph.D. thesis



Deterministic equation solving over finite fields (U. Leiden, 2006)

which you are welcome to take a copy of (just ask me).

The End